

# PGW

Sesame Motor PGW in-line planetary gearheads are designed to bolt-on linear actuator drive systems to shorten powertrain length. Dynamic balanced collar clamping mechanism to actuator and motor shaft ensuring interfaces concentrically and zero slip power transmission at high speed. High quality gears and components are utilized to create compact and rigid unit with low backlash and maintenance-free operation.

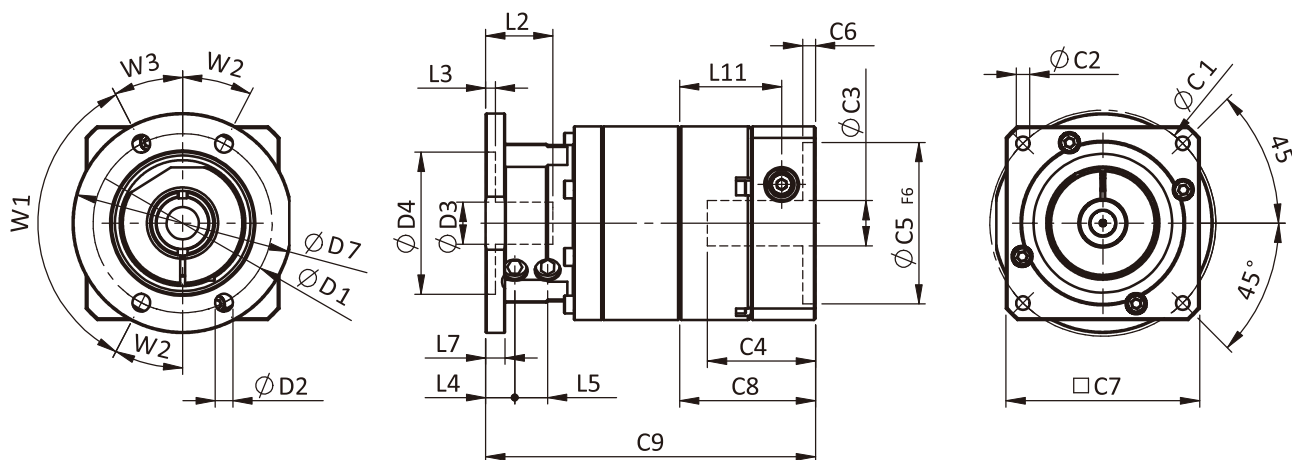


Frame Size (mm)	60, 90, 115
Ratio	3 : 1-1000:1
Nominal Input Speed (rpm)	2,500 - 4,000
Max Input Speed (rpm)	5,000 - 6,000
Backlash (arc-min)	1 Stage: 6 - 8 2 Stages: 8 - 10 3 Stages: 12
Noise Level (dBA / 1m)	63 - 67

## Features

- ▶ In-line planetary gearhead with zero slip clamping mechanism.
- ▶ Hollow output shaft and flange are ready to mount to belt or ball screw modules.
- ▶ One-piece planet carrier/output shaft.
- ▶ Alloy steel precision gears.
- ▶ Ratios up to 1000:1.
- ▶ Lubricated for life and IP65 sealing.
- ▶ Low noise, low vibration, maintenance-free under normal operating conditions.

# PGW Single Stage Dimensions



## Specifications

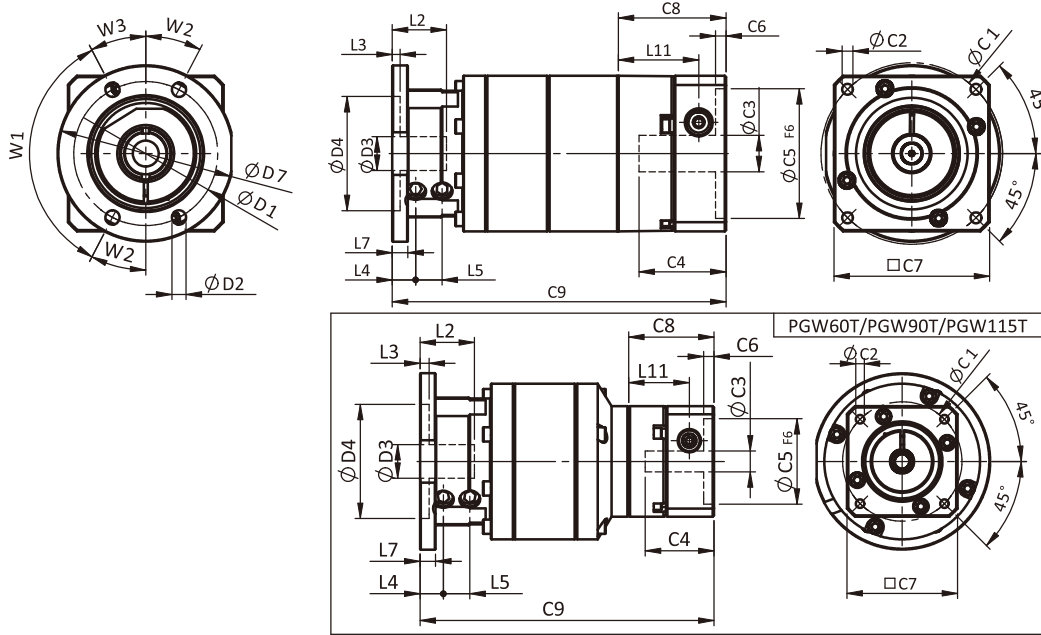
Unit:mm

Dimensions	PGW60	PGW90	PGW115
D1	55.5	73	105
D2	5.5	5.5	6.6
D3	16	20	30
D4	44	60	80
D7	70	84	118
L2	31	31	37
L3	3.5	3.5	3.5
L4	9	10.2	12.5
L5	10.2	10.9	13
L7	6	6	10
L11	31.6	37.3	51.8
W1	125°	90°	90°
W2	27.5°	22.5°	22.5°
W3	27.5°	67.5°	67.5°
C1 <sup>2</sup>	70	90	145
C2 <sup>2</sup>	M5x0.8P	M6x1.0P	M8x1.25P
C3 <sup>2</sup>	≤14/≤19	≤19/≤24/≤28	≤24/≤32/≤38
C4 <sup>2</sup>	33.5	41	51.5
C5 <sup>2</sup> F6	50	70	110
C6 <sup>2</sup>	4	6	6
C7 <sup>2</sup>	60	90	130
C8 <sup>2</sup>	42.1	51.5	68
C9 <sup>2</sup>	102.2	126.5	172

\* C1~C9 are motor specific dimensions (metric std shown). Size may vary according to motor flange.

\* Specification subject to change without notice.

# PGW Double Stage Dimensions



## Specifications

Unit:mm

Dimensions	PGW60	PGW60T	PGW90	PGW90T	PGW115T
D1	55.5		73		105
D2	5.5		5.5		6.6
D3	16		20		30
D4	44		60		80
D7	70		84		118
L2	31		31		37
L3	3.5		3.5		3.5
L4	9		10.2		12.5
L5	10.2		10.9		13
L7	6		6		10
L11	31	23.4	37.3	31	37.3
W1	125°		90°		90°
W2	27.5°		22.5°		22.5°
W3	27.5°		67.5°		67.5°
C1 <sup>2</sup>	70	46	90	70	90
C2 <sup>2</sup>	M5x0.8P	M4x0.7P	M6x1.0P	M5x0.8P	M6x1.0P
C3 <sup>2</sup>	≤14/≤19	≤8/≤11	≤19/≤24/≤28	≤14/≤19	≤19/≤24/≤28
C4 <sup>2</sup>	33.5	26.5	41	33.5	41
C5 <sup>2</sup> F6	50	30	70	50	70
C6 <sup>2</sup>	4	4	6	4	6
C7 <sup>2</sup>	60	42.6	90	60	90
C8 <sup>2</sup>	41.5	32.9	51.5	41.5	51.5
C9 <sup>2</sup>	128.6	113.3	160.3	145.8	193.6

★ C1~C9 are motor specific dimensions (metric std shown). Size may vary according to motor flange.

★ Specification subject to change without notice.

# PGW Specifications

Specifications		Stage	Ratio	PGW60	PGW90	PGW115	
Nominal Output Torque $T_{2N}$	N•m	1	3	28	85	200	
			4	32	80	215	
			5	35	95	215	
			7	28	85	200	
			9	23	75	195	
		10	21	65	180		
		Stage	Ratio	PGW60/PGW60T	PGW90/PGW90T	PGW115T	
		2	15	35/24	95/68	168	
			20	35/31	95/95	215	
			25	35/30	95/95	215	
			35	35/28	95/95	215	
			45	35/27	95/92	215	
			50	35/27	95/82	205	
			70	28/28	85/85	200	
			90	23/23	75/75	195	
		100	21/21	65/65	180		
		Stage	Ratio	PGW60T	PGW90T	PGW115T	
		3	125	35	95	215	
			175	35	95	215	
			225	35	95	215	
			245	35	95	215	
			315	35	95	215	
			405	35	95	215	
			567	28	85	200	
729	23		75	195			
1000	21	65	180				
Emergency Stop Torque $T_{2NOT}$	N•m	(2.5 times of Nominal Output Torque) (*Max. Output Torque $T_{2B}$ =60% of Emergency Stop Torque)					
Nominal Input Speed $n_{1N}$	rpm	1,2,3	3-1000	4000	3000	2500	
Max. Input Speed $n_{1max}$	rpm	1,2,3	3-1000	6000	6000	5000	
Standard Backlash P2	arcmin	1	3-10	≤ 8	≤ 7	≤ 6	
		2	15-100	≤ 10	≤ 9	≤ 8	
		3	125~1000	≤ 12	≤ 12	≤ 12	
Operating Temp.	°C	1,2,3	-10°C ~ +90°C				
Service Life	hr	1,2,3	3-1000	20,000 (10,000 Continuous operation)			
Efficiency	%	1	3-10	≥ 95%			
		2	15-100	≥ 90%			
		3	125~1000	≥ 85%			
Weight	kg	1	3-10	1.2	2.9	6.4	
		2	15-100	1.6/1.4	4.3/3.2	8.0	
		3	125~1000	1.8	4.6	9.4	
Mounting Position	-	1,2,3	3-1000	Any Direction			
Noise Level <sup>2</sup>	dB(A)/1m	1,2,3	3-1000	63	66	67	
Protection Class	-	1,2,3	3-1000	IP65			
Lubrication	-	1,2,3	3-1000	Synthetic Lubricant			
Inertia (J1)							
Stage	Ratio	unit	PGW60(φ14)	PGW90(φ19)	PGW115(φ24)		
1	3	kg•cm <sup>2</sup>	0.23	0.77	2.30		
	4		0.21	0.67	1.92		
	5~10		0.21	0.61	1.71		
Stage	Ratio		PGW60(φ14)/PGW60T(φ8)	PGW90(φ19)/PGW90T(φ14)	PGW115T(φ19)		
2	15		0.23/(0.04)	0.77/(0.23)	0.77		
	Other Ratios		0.21/(0.03)	0.61/(0.21)	0.61		
Stage	Ratio		PGW60T(φ8)	PGW90T(φ14)	PGW115T(φ19)		
3	All Ratios		0.03	0.21	0.61		
* 1. Applied to the output shaft center at 100 rpm.							
* 2. Environment noise level 30 dB; distance 1m; measured under free loading with input speed 3000 rpm; ratio = 10 (1-stage) or ratio = 100 (2-stage).							
※The above figures/specifications are subject to change without prior notice.							

Products due to human error, natural disasters or other factors lead to poor or damaged, will not be covered under warranty.